

Digital Image Processing Using MATLAB **3rd edition**

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ERRATA SHEET

Some of the corrections listed may already be incorporated in your printing of the book

Page	Reads	Should Read
76	The listing for function <code>imageStats2</code> should be: <pre>function G = imageStats2(f) G{1} = size(f); G{2} = mean2(f); G{3} = mean(f,2); G{4} = mean(f,1);</pre>	
147 Ten lines from bottom	0.5%	5%
150, 3 rd line of 2 nd full parag.	<code>lp = fir1(128,0.1)</code>	<code>lp = fir1(128,0.06)</code>
241 [Solution to Proj 4.1(a)] in your Support Package	<code>S = complex(SG,0)</code>	<code>SG = complex(SG,0)</code>
242 [Proj 4.2(b)]	$MNf^*(x,y) = F^*(u,v)$	$MNf^*(x,y) = DFT[F^*(u,v)]$
242 [Solution to Proj 4.3(c)] in the Faculty Support Package]	<code>figure, imshow(g3)</code> <code>figure, imshow(g4)</code>	<code>figure, imshow(g3,[])</code> <code>figure, imshow(g4,[])</code>
243 [Proj 4.5(a)]	<code>..FrequencyEmphasis(f,a,b,D0,n)</code>	<code>..FrequencyEmphasis(f,D0,n,a,b)</code>
244 [Proj 4.6(b)]	... Fig. 4.16(b).	... Fig. 4.15(b).
244 [Solution to Proj 4.7(a)] in your Support Package	Replace lines 52 & 53 with: <code>CC(:,1) = r0 + delr(:); & CC(:,2) = c0 + delc(:);</code>	
316, Proj. 5.1(c), line 2	Replace “in Eq. (5-13)” with (see the 1 st row in Table 5.1)	
317, Proj. 5.6(a), in the Example	... total of 32 squares in each size	... total of 32 squares in each side
317, Proj. 5.6(b), line 1	Replace “pixels in which each square has 8 pixels” by “8 squares”	
317, Proj. 5.6(b), line 2	Replace “a PSF” by “an OTF”	
374, Proj. 6.7(b)	Replace the word “resizing” by the word “reducing.”	
457	<code>basisImage</code>	<code>basisImages</code>
797	Two instances of <code>fchcode</code> should be <code>freemanChainCode</code> .	
857, Eq. (13-48), swap <i>b</i> & <i>c</i>	$\mathbf{H} = [a \ c; \ c \ b]$	$\mathbf{H} = [a \ b; \ b \ c]$

857, Eq. (13-50)	The square root should not enclose the denominator.	
980, Proj 14.3(b)	Figs. 14.4(g)-(i)	Figs. 14.5(g)-(i)

Revised function imrecon in Proj 5.10(a)

```
function g = imrecon(f,theta)
%IMRECON Image reconstruction from projections.
% G = IMRECON(F,THETA) creates projections of grayscale image F, then
% reconstructs the image using backprojections at the angles supplied
% in the 1-D array THETA. The angles in THETA are in degrees. These
% are the angles of the normal to the direction of the beam, measured
% counterclockwise with respect to the x-axis, as illustrated in Fig.
% 5.16. For example, to obtain a vertical projection, we use THETA = 0
% degrees.
%
% The output reconstructed image is square, of size equal to the long
% dimension of the input image. The output is scaled so the full
% intensity range [0,1].
%
% The objectives of this function are to illustrate conceptually the
% basics of image reconstruction from projections, as explained in
% Section 5.10.

% Preliminaries
% Generate a square image whose size will be the longest dimension of
% the original, as required in the function definition.
f = makeSquare(f);
M = size(f,1);
f = im2double(f);

% Pad f with a border of zeros, large enough to accommodate the largest
% possible rotated image. In general, for an image of size M x N, the
% vertical top and bottom padding are ceil((D-M)/2). For the horizontal,
% the padding the left and right padding are ceil((D-N)/2), where D is
% the diameter of the image. But our images have been padded to be
% square.
D = ceil(sqrt(M^2 + M^2));

% Make D an even integer so that padding strips will be of the same size
% on top, bottom, left, and right.
if isodd(D)
    D = D + 1;
end

% Padding value:
pad = ceil((D - M)/2);

% Pad the image
f = padarray(f,[pad,pad],0,'both');

% Beam(s) is(are) normal to angle(s) provided.
theta = theta + 90;

g = zeros(size(f));

smearLength = size(g,2);

% Projections and backprojections.

NL = numel(theta);

% A wait bar is included because this is a slow-running function for
% large images and/or a large number of angle increments.
bar = waitbar(0,'Working...');

for I = 1:NL
    % For simplicity, rotate image instead of the sensors, thus the use
    % of -theta below. This is equivalent to leaving the image stationary
    % and rotating the sensors.
    rot = imrotate(f,-theta(I),'bilinear','crop');

    % Sum rows to obtain projection.
    p = sum(rot,2);
```

```
% "Smear" the projections across image.
smear = repmat(p,1,smearLength);

% Rotate g to insert projection.
g = imrotate(g,-theta(I),'bilinear','crop');

% Insert projection.
g = g + smear;

% Rotate back.
g = imrotate(g,theta(I),'bilinear','crop');

waitbar(I/NL)
end

close(bar)

% Crop back to original size.
g = g(pad+1:pad+M, pad+1:pad+M);

% Scale output to the full [0,1] range.
g = intensityScaling(g);

%-----%
function g = makeSquare(f)

[M,N] = size(f);
D = abs(M - N);
if isodd(D)
    D = D + 1;
end
if M > N
    padVector = [0,D/2];
elseif M < N
    padVector = [D/2,0];
else
    padVector = [0,0];
end

% Pad the image.
f = padarray(f,padVector,0,'both');

% Dimensions could be off by 1 pixel. Make sure image is square.
[M,N] = size(f);
if M ~= N && M < N
    moreRows = N - M;
    % Make the image square by replicating rows.
    g = padarray(f,[moreRows,0],'replicate','post');
elseif M ~= N && M > N
    moreColumns = M - N;
    g = padarray(f,[0,moreColumns],'replicate','post');
else
    g = f;
end

%-----%
```